## Revision History

<table>
<thead>
<tr>
<th>Issue</th>
<th>Issue Date</th>
<th>Details of Change</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>December 2015</td>
<td>First Production release.</td>
</tr>
<tr>
<td>5</td>
<td>March 2016</td>
<td>V1.1.0 Beta Release.</td>
</tr>
<tr>
<td>6</td>
<td>April 2016</td>
<td>V1.1.0 Production Release RTP.</td>
</tr>
<tr>
<td>7</td>
<td>September 2016</td>
<td>V1.2.0 Production Release RTP; fix connector info on HBA-1000 16i/8i board diagrams to match PCB silkscreen notation; add 16i bay mapping; remove DKMS driver installs, refer to Readme.</td>
</tr>
<tr>
<td>8</td>
<td>June 2017</td>
<td>Updated for 1.4 maintenance release.</td>
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Microsemi Adaptec® Product Support

If you have questions about installing or using your Microsemi Adaptec® product, check this document first—you will find answers to most of your questions. If you need further assistance, use the support options listed below. To expedite your service, have your computer in front of you.

**Note:** Please visit the Support section of www.adaptec.com for the most up to date contact information.

### Self Help and Support in English

- Visit our Web site at [www.adaptec.com](http://www.adaptec.com).
- Search the Adaptec Support Knowledgebase (ASK) at ask.adaptec.com for articles, troubleshooting tips, and frequently asked questions for your product.
- For support through email, submit your question at ask.adaptec.com.
- To contact Technical Support, visit our product support site at storage.microsemi.com/en-us-support/.

### Technische Informationen und Support in Deutsch

- Besuchen Sie unsere Webseite [www.adaptec.com/de-de](http://www.adaptec.com/de-de).
- Suchen Sie in der Adaptec Support Knowledgebase (ASK) unter ask-de.adaptec.com nach Artikeln, Tipps zur Fehlerbehebung und häufig gestellten Fragen zu Ihrem Produkt.
- Support per Email erhalten Sie unter ask-de.adaptec.com.
- Um den Technischen Support zu kontaktieren, besuchen Sie uns bitte unter start.microsemi.com und klicken Sie auf „Support kontaktieren”, für Auswahlmöglichkeiten.

### Техническая поддержка и информация на русском языке

- База знаний Adaptec (ASK) на сайте ask-ru.adaptec.com ask-ru.adaptec.com – статьи, советы по устранению неисправностей и часто задаваемые вопросы о Вашем продукте.
- Для поддержки по электронной почте отправьте Ваш запрос на сайте ask-ru.adaptec.com
- Для обращения в службу Технической Поддержки, пожалуйста, посетите наш web сайт start.microsemi.com и используйте ссылку "Contact Support".

### 日本語での技術情報とサポート

- 弊社のウェブサイト、www.adaptec.com/ja-jp をご覧ください。
- ask.adaptec.co.jp のAdaptec Support Knowledgebase (ASK)で、お使いの製品の情報 トラブルシューティングのヒント、よくある質問を検索してください。
- Eメールでのサポートには ask.adaptec.co.jp から質問を送ってください。
- テクニカルサポートへコントクトするには、弊社ウェブサイト start.microsemi.comをご覧になり、"Contact Support”をクリックして下さい。
Limited 3-Year Hardware Warranty

1. Microsemi Corporation ("Microsemi") warrants to the purchaser of this product that it will be free from defects in material and workmanship for a period of three (3) years from the date of purchase. If the product should become defective within the warranty period, Microsemi, at its option, will repair or replace the product, or refund the purchaser’s purchase price for the product, provided it is delivered at the purchaser’s expense to an authorized Microsemi service facility or to Microsemi.

2. Repair or replacement parts or products will be furnished on an exchange basis and will either be new or reconditioned and will be subject to original warranty term. All replaced parts or products shall become the property of Microsemi. This warranty shall not apply if the product has been damaged by accident, misuse, abuse or as a result of unauthorized service or parts.

3. Warranty service is available to the purchaser by delivering the product during the warranty period to an authorized Microsemi service facility or to Microsemi and providing proof of purchase price and date. The purchaser shall bear all shipping, packing, and insurance costs and all other costs, excluding labor and parts, necessary to effectuate repair, replacement or refund under this warranty.

4. For more information on how to obtain warranty service, click on the Services & Support link at microsemi.com.

5. THIS LIMITED WARRANTY DOES NOT EXTEND TO ANY PRODUCT WHICH HAS BEEN DAMAGED AS A RESULT OF ACCIDENT, MISUSE, ABUSE, OR AS A RESULT OF UNAUTHORIZED SERVICE OR PARTS.

6. THIS WARRANTY IS IN LIEU OF ALL OTHER EXPRESS WARRANTIES WHICH NOW OR HEREAFTER MIGHT OTHERWISE ARISE RESPECT TO THIS PRODUCT. IMPLIED WARRANTIES, INCLUDING THOSE OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NON-INFRINGEMENT SHALL (A) HAVE NO GREATER DURATION THAN 3 YEARS FROM THE DATE OF PURCHASE, (B) TERMINATE AUTOMATICALLY AT THE EXPIRATION OF SUCH PERIOD AND (C) TO THE EXTENT PERMITTED BY LAW BE EXCLUDED. IN THE EVENT THIS PRODUCT BECOMES DEFECTIVE DURING THE WARRANTY PERIOD, THE PURCHASER’S EXCLUSIVE REMEDY SHALL BE REPAIR, REPLACEMENT OR REFUND AS PROVIDED ABOVE. INCIDENTAL OR CONSEQUENTIAL DAMAGES, INCLUDING WITHOUT LIMITATION LOSS OF DATA, ARISING FROM Breach OF ANY EXPRESS OR IMPLIED WARRANTY ARE NOT THE RESPONSIBILITY OF MICROSEMI AND, TO THE EXTENT PERMITTED BY LAW, ARE HEREBY EXCLUDED BOTH FOR PROPERTY DAMAGE, AND TO THE EXTENT NOT UNCONSCIONABLE, FOR PERSONAL INJURY DAMAGE.

7. WITHIN THE US, SOME STATES DO NOT ALLOW THE EXCLUSION OR LIMITATION OF INCIDENTAL OR CONSEQUENTIAL DAMAGES FOR CONSUMER PRODUCTS, AND SOME STATES DO NOT ALLOW LIMITATIONS ON HOW LONG AN IMPLIED WARRANTY LASTS, SO THE ABOVE LIMITATION OR EXCLUSIONS MAY NOT APPLY TO YOU.

8. THIS WARRANTY GIVES YOU SPECIFIC LEGAL RIGHTS, AND YOU MAY ALSO HAVE OTHER RIGHTS WHICH VARY DEPENDING ON WHERE YOU RESIDE.

9. FOR AUSTRALIA RESIDENTS, IF THE PRODUCT SHOULD BECOME DEFECTIVE WITHIN THE WARRANTY PERIOD, MICROSEMI, AT ITS OPTION, WILL REPAIR OR REPLACE THE PRODUCT, OR REFUND THE PURCHASER’S PURCHASE FOR THE PRODUCT, PROVIDED IT IS DELIVERED AT THE PURCHASER’S EXPENSE BACK TO THE PLACE OF PURCHASE AFTER MICROSEMI TECHNICAL SUPPORT HAS ISSUED AN INCIDENT NUMBER. IN ADDITION TO THE WARRANTIES SET FORTH HEREIN, OUR GOODS COME WITH GUARANTEES THAT CANNOT BE EXCLUDED UNDER THE AUSTRALIAN CONSUMER LAW. YOU ARE ENTITLED TO A REPLACEMENT OR REFUND FOR A MAJOR FAILURE AND FOR COMPENSATION FOR ANY OTHER REASONABLY FORESEEABLE LOSS OR DAMAGE. YOU ARE ALSO ENTITLED TO HAVE THE GOODS REPAIRED OR REPLACED IF THE GOODS FAIL TO BE OF ACCEPTABLE QUALITY AND THE FAILURE DOES NOT AMOUNT TO A MAJOR FAILURE.
Regulatory Compliance Statements

Federal Communications Commission Radio Frequency Interference Statement

Attention: Changes or modifications to this unit not expressly approved by the party responsible for compliance could void the user’s authority to operate the equipment.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses, and can radiate radio frequency energy, and if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. However, if this equipment does cause interference to radio or television equipment reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between equipment and receiver.
- Connect the equipment to an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/television technician for help.
- Use a shielded and properly grounded I/O cable and power cable to ensure compliance of this unit to the specified limits of the rules.

This device complies with part 15 of the FCC rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference and (2) this device must accept any interference received, including interference that may cause undesired operation.

UL Compliance Statement

Microsemi Adaptec products are tested and listed by Underwriters Laboratories, Inc. to UL 60950-1 Second Edition and IEC-60950-1 Second Edition standards, file numbers E175975. Microsemi Adaptec products are for use only with UL listed ITE.

Microsemi Corporation

Use only with the listed ITE:

- Microsemi Adaptec HBA 1000-16i/Microsemi Adaptec HBA 1000-8i8e/
- Microsemi Adaptec HBA 1000-8i/Microsemi Adaptec HBA 1000-8e/
- Microsemi Adaptec HBA 1000-16e

Microsemi Proprietary and Confidential Document Number: PMC-2152188, Issue 8
European Union Compliance Statement

This Information Technology Equipment has been tested and found to comply with EMC Directive 2014/30/EU, in accordance with:

- EN55032 (2014) Emissions:
  - Class B ITE radiated and conducted emissions
- EN55024 (2010) Immunity:
  - EN61000-4-2 (2009) Electrostatic discharge: ±4 kV contact, ±8 kV air
  - EN61000-4-3 (2010) Radiated immunity: 3V/m
  - EN61000-4-4 (2012) Electrical fast transients/burst: ±1 kV AC, ±0.5 kV I/O
  - EN61000-4-5 (2014) Surges: ±1 kV differential mode, ±2 kV common mode
  - EN61000-4-6 (2014) Conducted immunity: 3 V
  - EN61000-4-11 (2004) Supply dips and variations: 30% and 100%
- EN50581 (2012) Technical Documentation:
  - For the assessment of electrical and electronic products with respect to the restriction of hazardous substances

In addition, all equipment requiring U.L. listing has been found to comply with EMC Directive 2014/35/EU, in accordance with EN60950 with amendments A1, A2, A3, A4, A11, A12.

Australian/New Zealand Compliance Statement

This device has been tested and found to comply with the limits for a Class B digital device, pursuant to the Australian/New Zealand standard AS/NZS 3548 set out by the Spectrum Management Agency.

Canadian Compliance Statement

This Class B digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations.
Cet appareil numérique de la classe B respecte toutes les exigences du Règlement sur le matériel brouilleur du Canada.

Japanese Compliance (Voluntary Control Council Initiative)

This equipment complies to class B Information Technology equipment based on VCCI (Voluntary Control Council for Interface). This equipment is designed for home use but it may causes radio frequency interference problem if used too near to a television or radio. Please handle it correctly per this documentation.

Korean Compliance (KCC) Statement

Microsemi Adaptec products are tested and certified by KCC:

MSIP-REM-KHK-1000-8i8e

The above certification covers the following series:

- Microsemi Adaptec HBA 1000-16i, Microsemi Adaptec HBA 1000-8i8e,
- Microsemi Adaptec HBA 1000-8i, Microsemi Adaptec HBA 1000-8e,
- Microsemi Adaptec HBA 1000-16e
This equipment is home use (Class B) electromagnetic wave suitability equipment and to be used mainly at home and it can be used in all areas.
1 About This Guide

This Installation and User's Guide explains how to install and setup your Microsemi® Adaptec® HBA 1000 Series Host Bus Adapter, including driver installation and use of the BIOS-based PMC SAS/SATA Configuration utility. It also provides troubleshooting tips and instructions for flashing the HBA 1000 Series firmware.

These Microsemi Adaptec HBA 1000 Series models are described in this guide:

- Microsemi Adaptec HBA 1000-8i
- Microsemi Adaptec HBA 1000-8e
- Microsemi Adaptec HBA 1000-8i8e
- Microsemi Adaptec HBA 1000-16i
- Microsemi Adaptec HBA 1000-16e

1.1 What You Need to Know Before You Begin

This guide is written for data storage and IT professionals who are responsible for installing, configuring, and maintaining HBA 1000 Series Host Bus Adapters in computers or servers in a "cloud" or data center environment. You should be familiar with computer hardware, operating system administration, data storage devices, and SAS and Serial ATA (SATA) technology.

1.2 Terminology Used in this Guide

Many of the terms and concepts referred to in this guide are known to computer users by multiple names. This guide uses these terms:

- Host Bus Adapter or HBA (also known as controller, adapter, or I/O card)
- Disk drive (also known as hard disk, hard drive, or hard disk drive)
- Solid State Drive (also known as SSD or non-rotating storage media)
- Enclosure (also known as a storage enclosure, disk drive enclosure, or JBOD)

1.3 How to Find More Information

You can find more information about your HBA 1000 Series Host Bus Adapter by referring to these documents, available for download at start.microsemi.com.

- Microsemi Adaptec Host Bus Adapter 1000 Series Release Notes—Includes updated product information and known issues and limitations. (PMC-2152169)
- Microsemi Adaptec Host Bus Adapter 1000 Series Command Line Utility User's Guide—Describes how to use the ARCCONF utility to perform configuration and storage management tasks from an interactive command line. (PMC-2152156)
- Microsemi Adaptec HBA 1000 Series Host Bus Adapters Installation and User's Guide (this manual)—Describes how to install drivers and configure the HBA 1000 Series adapter for initial use. (PMC-2152188)
2 Kit Contents and System Requirements

This section lists the contents of your Microsemi Adaptec HBA 1000 Series kit and the system requirements for successfully installing and using your HBA.

2.1 Kit Contents

- Microsemi Adaptec HBA 1000 Series adapter
- Low-profile bracket

Note: The latest firmware, drivers, utilities software, and documentation can be downloaded at start.microsemi.com. For more information, see Downloading the Driver Package on page 24.

2.2 System Requirements

- PC-compatible computer with Intel Pentium, or equivalent, processor
- 4 GB of RAM minimum
- Available compatible PCIe slot (depending on your adapter model—see the descriptions in About Your Host Bus Adapter)
- One of these operating systems:
  - Red Hat® Enterprise Linux
  - CentOS
  - SuSE Linux Enterprise Server
  - Ubuntu Linux
  - Oracle Linux
  - Citrix Xenserver
  - VMware ESXi

See the Release Notes for a complete list of supported OS versions.
- USB flash drive or CD burner, for creating driver disks and bootable media
### 3 About Your Host Bus Adapter

This section provides an overview of the features of the Microsemi Adaptec HBA 1000 Series adapter.

#### 3.1 Standard Features

- Support for SAS and SATA HDDs, Solid State Drives (SSDs), removable media, and SAS tape drives
- uEFI pre-boot BIOS, CTRL-A configuration utility
- Flash ROM for updates to firmware and BIOS
- up to 16 ports, 12 Gbps I/O
- SAS 3.0, PCIe 3.0
- Low-profile MD2 form factor
- Mini-SAS HD connectors
- Support for disk drive enclosures with SES2 enclosure management hardware
- Thermal sensor with logging capabilities

#### 3.2 Mechanical Information

##### 3.2.1 Board Dimensions

This table shows the board dimensions of the Microsemi Adaptec Host Bus Adapter 1000 Series, in inches.

<table>
<thead>
<tr>
<th>Measure</th>
<th>Dimension</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.535&quot;</td>
<td>Height</td>
</tr>
<tr>
<td>6.60&quot;</td>
<td>Length</td>
</tr>
<tr>
<td>0.62&quot;</td>
<td>PCB Thickness</td>
</tr>
<tr>
<td>0.570&quot;</td>
<td>Max Component Height, Top Side</td>
</tr>
<tr>
<td>0.105&quot;</td>
<td>Max Component Height, Bottom Side</td>
</tr>
</tbody>
</table>

##### 3.2.2 Heat Sink

HBA 1000 Series adapters include a passive heat sink capable of bi-directional airflow. For airflow requirements, see Environmental Specifications on page 45.
3.3 Visual Indicators

HBA 1000 Series adapters include three status LEDs on the back of the printed circuit board (Figure 1 • HBA 1000 Status LEDs). The LEDs signify the status of the actions described in Table 2 • Status LEDs.

Figure 1 • HBA 1000 Status LEDs

Table 2 • Status LEDs

<table>
<thead>
<tr>
<th>LED</th>
<th>Color</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>DS1</td>
<td>Orange</td>
<td>Unused</td>
</tr>
<tr>
<td>DS2</td>
<td>Red/Amber</td>
<td>Lockup/Fault (This LED should be lit only when the firmware hits a lockup)</td>
</tr>
<tr>
<td>DS3</td>
<td>Green</td>
<td>Heartbeat (1Hz blinking when firmware operating normally)</td>
</tr>
</tbody>
</table>
3.4 About the Microsemi Adaptec HBA 1000-8i

The Microsemi Adaptec HBA 1000-8i is a SAS Host Bus Adapter with these features:

- Form Factor: Low-profile MD2
- Bus compatibility: PCIe 3.0
- PCIe bus width: x8
- Data transfer rate: 12 Gbps per port
- Phys (Unified Serial Ports): 8
- Standard memory: 16 MB Boot Flash
- Connectors, internal: 2 mini-SAS HD x4 (SFF-8643)
- Maximum number of disk drives: 8 direct-attached (or up to 238 with expanders)
- Enclosure Support: IBPI and SGPIO
- Thermal sensor: Processor temperature

![Diagram of the Adaptec HBA 1000-8i with labeled connections](image)
3.5 About the Microsemi Adaptec HBA 1000-8e

The Microsemi Adaptec HBA 1000-8e is a SAS Host Bus Adapter with these features:

- 2 External mini-SAS HD connectors (CN0, CN1)
- HDA Mode connector
- PCIe x8 connector
- Mounting bracket

<table>
<thead>
<tr>
<th>Feature</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Form Factor</td>
<td>Low-profile MD2</td>
</tr>
<tr>
<td>Bus compatibility</td>
<td>PCIe 3.0</td>
</tr>
<tr>
<td>PCIe bus width</td>
<td>x8</td>
</tr>
<tr>
<td>Data transfer rate</td>
<td>12 Gbps per port</td>
</tr>
<tr>
<td>Phys (Unified Serial Ports)</td>
<td>8</td>
</tr>
<tr>
<td>Standard memory</td>
<td>16 MB Boot Flash</td>
</tr>
<tr>
<td>Connectors, external</td>
<td>2 mini-SAS HD x4 (SFF-8644)</td>
</tr>
<tr>
<td>Maximum number of disk drives</td>
<td>8 direct-attached (or up to 238 with expanders)</td>
</tr>
<tr>
<td>Enclosure Support</td>
<td>IBPI and SGPIO</td>
</tr>
<tr>
<td>Thermal sensor</td>
<td>Processor temperature</td>
</tr>
</tbody>
</table>
3.6 About the Microsemi Adaptec HBA 1000-16e

The Microsemi Adaptec HBA 1000-16e is a SAS Host Bus Adapter with these features:

- **Form Factor**: Low-profile MD2
- **Bus compatibility**: PCIe 3.0
- **PCIe bus width**: x8
- **Data transfer rate**: 12 Gbps per port
- **Phys (Unified Serial Ports)**: 8
- **Standard memory**: 16 MB Boot Flash
- **Connectors, external**: 4 mini-SAS HD x4 (SFF-8644)
- **Maximum number of disk drives**: 16 direct-attached (or up to 238 with expanders)
- **Enclosure Support**: IBPI and SGPIO
- **Thermal sensor**: Processor temperature
3.7 About the Microsemi Adaptec HBA 1000-8i8e

The Microsemi Adaptec HBA 1000-8i8e is a SAS Host Bus Adapter with these features:

![Diagram of the Microsemi Adaptec HBA 1000-8i8e]

- 2 Internal mini-SAS HD connectors (CN0, CN1)
- 2 External mini-SAS HD connectors (CN2, CN3)
- HDA Mode connector
- PCIe x8 connector
- Mounting bracket

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Form Factor</td>
<td>Low-profile MD2</td>
</tr>
<tr>
<td>Bus compatibility</td>
<td>PCIe 3.0</td>
</tr>
<tr>
<td>PCIe bus width</td>
<td>x8</td>
</tr>
<tr>
<td>Data transfer rate</td>
<td>12 Gbps per port</td>
</tr>
<tr>
<td>Phys (Unified Serial Ports)</td>
<td>16</td>
</tr>
<tr>
<td>Standard memory</td>
<td>16 MB Boot Flash</td>
</tr>
<tr>
<td>Connectors, internal</td>
<td>2 mini-SAS HD x4 (SFF-8643)</td>
</tr>
<tr>
<td>Connectors, external</td>
<td>2 mini-SAS HD x4 (SFF-8644)</td>
</tr>
<tr>
<td>Maximum number of disk drives</td>
<td>16 direct-attached (or up to 238 with expanders)</td>
</tr>
<tr>
<td>Enclosure Support</td>
<td>IBPI and SGPIO</td>
</tr>
<tr>
<td>Thermal sensor</td>
<td>Processor temperature</td>
</tr>
</tbody>
</table>
3.8 About the Microsemi Adaptec HBA 1000-16i

The Microsemi Adaptec HBA 1000-16i is a SAS Host Bus Adapter with these features:

- 2 Internal mini-SAS HD connectors (CN0, CN1)
- 2 Internal mini-SAS HD connectors (CN2, CN3)
- HDA Mode connector
- PCIe x8 connector
- Mounting bracket

### Form Factor
- Low-profile MD2

### Bus compatibility
- PCIe 3.0

### PCIe bus width
- x8

### Data transfer rate
- 12 Gbps per port

### Phys (Unified Serial Ports)
- 16

### Standard memory
- 16 MB Boot Flash

### Connectors, internal
- 4 mini-SAS HD x4 (SFF-8643)

### Maximum number of disk drives
- 16 direct-attached (or up to 238 with expanders)

### Enclosure Support
- iBPI and SGPIO

### Thermal sensor
- Processor temperature

#### Table 3 • HBA 1000-16i Bay Mapping

<table>
<thead>
<tr>
<th>Connector</th>
<th>Bay Mapping</th>
</tr>
</thead>
<tbody>
<tr>
<td>CN1</td>
<td>Bay 13-16</td>
</tr>
<tr>
<td>CN0</td>
<td>Bay 9-12</td>
</tr>
<tr>
<td>CN2</td>
<td>Bay 5-8</td>
</tr>
<tr>
<td>CN3</td>
<td>Bay 1-4</td>
</tr>
</tbody>
</table>
4 Installing the Controller and Disk Drives

This section explains how to install your Microsemi Adaptec HBA 1000 Series adapter in a computer cabinet or server and connect it to internal and external disk drives.

4.1 Before You Begin

- Read Safety Information on page 44.
- Familiarize yourself with your HBA’s physical features (see Standard Features).
- Ensure that you have the right number of disk drives for your application (see Selecting Disk Drives and Cables on page 21).

4.2 Selecting Disk Drives and Cables

4.2.1 Disk Drives

Your Microsemi Adaptec RAID controller supports SAS and SATA disk drives, Solid State Drives (SSDs), and SAS tape drives. For more information about compatible disk drives, refer to www.adaptec.com/compatibility.

4.2.2 Cables

Depending on your HBA model and application requirements, you can use any of the cables listed below. For more information about cabling options for your HBA 1000 series adapter, visit www.adaptec.com/en-us/products/cables.

**Note:** We recommend using Microsemi Adaptec SAS cables only.

**SAS HD Cables**

- Internal SAS HD to SAS HD (SFF-8643 to SFF-8643) — Connects to a backplane or enclosure.
- External SAS HD to SAS HD (SFF-8644 to SFF-8644) — Connects to a backplane or enclosure.
4.3 Installing the Host Bus Adapter

This section describes how to install the HBA 1000 Series adapter into your computer cabinet or server. Microsemi Adaptec HBA 1000 Series adapters have three configurations:

- Adapters with internal connectivity
- Adapters with external connectivity
- Adapters with internal and external connectivity

Follow the steps below to install your HBA and connect internal and external storage devices.

1. Turn off your computer and disconnect the power cord and any network cables. Open the cabinet, following the manufacturer's instructions.

2. Select an available PCIe expansion slot that's compatible with your HBA and remove the slot cover, as shown in the figure below. (To check PCIe bus compatibility of your HBA, see About Your Host Bus Adapter on page 14.)

   **Caution:** Touch a grounded metal object before handling the adapter.

3. Insert the HBA into the expansion slot and press down gently but firmly until it clicks into place. When installed properly, the adapter should appear level with the expansion slot.

   **Caution:** Be sure to handle the adapter by its bracket or edges only. Apply pressure only on the edges when inserting the card into expansion slot.
4. Secure the bracket in the expansion slot, using the retention device (for instance, a screw or lever) supplied with your computer.

5. Connect SAS HD cables between the HBA and internal or external storage devices, as required:
   - For an HBA with external ports, connect SAS HD cables between the HBA and external disk drives or enclosures:

   ![External Ports, Front view]

   - For an HBA with internal ports, connect SAS HD cables between the HBA and internal disk drives or enclosures:

   ![Internal Ports, Front view]

   - For an HBA with internal and external ports, connect SAS HD cables between the HBA and internal and external disk drives or enclosures.

6. Close your computer cabinet, reconnect the power cord and network cables, then power up the system.
5 Installing the Driver and an Operating System

This chapter explains how to install the Microsemi Adaptec HBA 1000 Series adapter driver while installing the operating system.

Note:
1. To install the driver on an existing operating system, see Installing the Driver on an Existing Operating System on page 29.
2. To install the Linux drivers from source with Dynamic Kernel Module Support (for persistence across across kernel updates), download the Linux Driver Source Code package from the support page for your product at start.microsemi.com, then follow the instructions in the embedded Readme.

5.1 Download the Driver Package

Complete these steps to download the drivers for your operating system(s):

1. Open a browser window, then type start.microsemi.com in the address bar.
2. Enter your product or adapter model number, then select HBA 1000.
3. Select your operating system version, for instance, Microsoft Windows Server 2012 x64 or Red Hat Enterprise Linux 7; then select the appropriate driver from the list.
4. Download the HBA 1000 Series driver package.
5. When the download completes, extract the package contents to a temporary location on your machine. Each driver is stored in a separate folder (\windows 2012, \rhel6, \rhel7, and so on).

   Note: See the Release Notes for a complete list of available driver files.

5.2 Creating a Driver Disk

Create a driver disk by completing the steps below. You will need a USB flash drive to complete this task.

Note: For VMware and XenServer, see Installing with VMware and Installing with Citrix XenServer on page 28.

1. Change to the driver directory for your operating system version.
2. Write the driver binary file to a USB flash drive (assuming the USB drive is /dev/sdc on Linux systems).

   Options  Description
   
   rhel6/centos6  gunzip hpsa-3.4.10-110.rhel6u5.x86_64.dd.gz
dd if=hpsa-3.4.10-110.rhel6u5.x86_64.dd of=/dev/sdc

   rhel7/centos7  gunzip hpsa-3.4.10-115.rhel7u0.x86_64.dd.gz
dd if=hpsa-3.4.10-115.rhel7u0.x86_64.dd of=/dev/sdc

   sles11  gunzip hpsa-3.4.10-110.sles11sp3.x86_64.dd.gz
dd if=hpsa-3.4.10-110.sles11sp3.x86_64.dd of=/dev/sdc
### Installing the Driver and an Operating System

<table>
<thead>
<tr>
<th>Options</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>sles12</td>
<td>gunzip hpsa-3.4.10-110.sles12sp0.x86_64.dd.gz</td>
</tr>
<tr>
<td></td>
<td>dd if=hpsa-3.4.10-110.sles12sp0.x86_64.dd of=/dev/sdc</td>
</tr>
<tr>
<td>ubuntu14.04</td>
<td>gunzip hpsa-3.4.11-100.ubuntu14.04.x86_64.img.gz</td>
</tr>
<tr>
<td></td>
<td>dd if=hpsa-3.4.11-100.ubuntu14.04.x86_64.img.gz of=/dev/sdc1</td>
</tr>
<tr>
<td>windows</td>
<td>winzip HpCISSs3.4.10.110.64_pass4.zip</td>
</tr>
<tr>
<td></td>
<td>cp hpsa.inf hpsa2.inf &lt;usb drive&gt;</td>
</tr>
</tbody>
</table>

3. Remove and label the driver disk.
4. Continue the installation with the instructions for your operating system.

#### 5.3 Installing with Windows

**Note:** Use the following procedure for all supported Windows versions. You will need your Windows Installation DVD (or equivalent virtual media/iso image) to complete this task.

To install the RAID controller driver while installing Windows:

1. Insert the Windows installation DVD, then restart the computer.
2. Follow the on-screen instructions to begin the Windows installation.
3. When prompted to specify a location for Windows, select **Load Driver**.
4. Insert the USB driver disk, browse to the driver location, then click **Ok**.
5. When prompted to select the driver to install, click **Next**. (You will see two drivers in the list; it doesn’t matter which driver is selected.)
6. Click **Next** again to accept the default partition configuration.
7. Follow the on-screen instructions to complete the installation.

#### 5.4 Installing with Red Hat Linux, or CentOS, or Oracle Linux

**Note:** You will need your installation DVD (or equivalent virtual media/iso image) to complete this task. You must have root privilege to install the driver image.

To install the RAID controller driver while installing Red Hat Linux, or CentOS, or Oracle Linux:

1. Insert your installation CD.
2. Restart your computer.
3. When the first installation screen appears, insert the USB driver disk.
4. Type this command at the Boot: prompt, then press **Enter**:
   ```
   linux dd
   ```
5. Select **Yes** to indicate that you have a driver disk, browse the USB drive (typically, `/dev/sda1`), then select the driver image.
6. Verify that the driver is loaded, then complete the installation following the on-screen instructions.

#### 5.5 Installing with SuSE Linux Enterprise Server

**Note:** You will need the SuSE installation DVD (or equivalent virtual media/iso image) to complete this task. You must have root privilege to install the driver image.

To install the RAID controller driver while installing SuSE Linux:
1. Insert the SuSE Installation DVD.
2. Restart your system.
3. When the installation selection screen appears, choose the type of installation you want, press F6, then select Yes to indicate that you have a driver disk.
4. Insert the USB driver disk.
5. *(SuSE 11 SP3 32-bit, 64-bit)* Add 'brokenmodules=aacraid dud=1' to the Boot menu. This step ensures that the installer loads from the driver disk, not the in-box driver.
6. When prompted to "Please choose the Driver Update medium", highlight the USB partition, then select OK.
   
   **Note:** If the "choose Driver Update medium" screen is displayed again, assume that the driver was accepted; select Back, then press Enter.

7. *(SuSE 11 SP3 32-bit, 64-bit)* On the "Welcome screen", switch to the console by typing CTRL+ALT+F2, then type this command:

   ```
   insmod ./update/000/modules/aacraid.ko
   ```

   Press CTRL+ALT+F7 to return to the Welcome screen.

8. Complete the installation, following the on-screen instructions.

### 5.6 Installing with Ubuntu Linux

**Note:** You will need the Ubuntu installation DVD (or equivalent virtual media/iso image) to complete this task. You must have root privilege to install the driver image.

**Note:** Microsemi's pre-built driver supports the kernel that is delivered as part of the ISO. For other kernels, use DKMS process.

To install the RAID controller driver while installing Ubuntu Linux:

1. Insert the Ubuntu Installation DVD, then restart your computer.
2. When the installation menu appears, select **Install Ubuntu Server**. Continue the installation until the "Configure Network" screen appears, then type CTRL+ALT+F2 to switch to the console.
3. Insert the USB driver disk.
4. Assuming the USB drive is assigned to /dev/sda1, type the following commands to begin loading the driver:

   ```
   mkdir mnt2 /AACRAID
   mount /dev/sda1 /mnt2
   cp -R /mnt2/* /AACRAID
   umount /mnt2
   ```

5. Copy the driver file to the /lib/modules directory:

   ```
   rmmod aacraid
   cp -f /AACRAID/aacraid.ko
   /lib/modules/3.16.0-23-generic/kernel/drivers/scsi/aacraid/aacraid.ko
   ```

6. Remove the USB drive.
7. Install the loadable module:

   ```
   insmod /lib/modules/3.16.0-23-generic/kernel/drivers/scsi/aacraid/aacraid.ko
   ```

8. Press CTRL+ALT+F1 to switch back to the installation screen, then follow the on-screen prompts to continue the installation.

   **Note:** Do not press Continue at the end of the installation until you complete Step [9]!
9. When prompted to reboot the system, press CTRL+ALT+F2 to switch to the console.

10. Type the following commands to complete the driver installation:

   Ubuntu 64-bit:
   
   ```
   cp -f /AACRAID/aacraid.ko
   /target/lib/modules/3.16.0-23-generic/kernel/drivers/scsi/aacraid/aacraid.ko
   chroot /target
   /sbin/depmod -a 2.6.32-28-server
   update-initramfs -u -v
   exit
   ```

11. Press CTRL+ALT+F1 to switch back to the installation screen, then reboot.

### 5.7 Installing with VMware

**Note:** You will need a writable CD or USB flash drive to complete this task. You must have administrator privileges to create the driver disk and install the driver image.

To install the RAID controller driver with VMware ESXi 6.0 or VMware ESXi 6.5, you must create a custom boot image using the ESXi-Customizer tool. This tool automates the process of customizing the ESXi install-ISO and runs as a script under Microsoft PowerShell.

You can download the ESXi-Customizer tool, ESXi-Customizer-PS-v2.5.ps1, from [https://www.v-front.de/p/esxi-customizer-ps.html](https://www.v-front.de/p/esxi-customizer-ps.html) and other locations on the Web.

**Note:** Be sure to install the prerequisite software first, including Powershell and VMware POWERCLI, before you install ESXi-Customizer.

**Note:** VMware 6.0 driver supports VMware 6.5.

To install the RAID controller driver while installing VMware:

1. Download and install Microsoft PowerShell and VMware POWERCLI, as needed. You can download PowerShell from the Microsoft Download Center at [www.microsoft.com/download](http://www.microsoft.com/download), and POWERCLI from [my.vmware.com](http://my.vmware.com).
   
   **Note:** PowerShell is pre-installed on many Windows systems, including Windows Server 2012 and Windows Server 2016.

2. Download the ESXi-Customizer tool from [https://www.v-front.de/p/esxi-customizer-ps.html](https://www.v-front.de/p/esxi-customizer-ps.html) or other Web location. Then, unpack the archive to a local directory on your Windows system; C:\ESXi-Customizer, for instance.

3. Copy the VMware driver vib for your OS version to a temp directory, such as C:\temp\pkg. The driver vib files (listed below, where xxxxxxx is the driver version number) should be in the driver download directory on your Windows system (see Creating a Driver Disk).

<table>
<thead>
<tr>
<th>Options</th>
<th>Description</th>
</tr>
</thead>
</table>
   | ESXi 6.5/6.0 | VMware-VMvisor-Installer-6.0.0-2494585.x86_64.iso  
               | vmware-esxi-drivers-scsi-aacraid-600.6.2.1.XXXXX.-1.0.6.2159203.x86_64.vib |

4. Run ESXi-Customizer from the installation directory:

   C:\ESXi-Customizer>ESXi-Customizer.cmd

5. In PowerShell, enter the following command:

   ```
   .\ESXi-Customizer-PS-v2.5.ps1 -Vxx -pkgDir C:\temp\pkg
   ```

   where Vxx is the VMware OS version: V60 for VMware 6.0, V65 for VMware 6.5.

   PowerShell begins creating the custom ESXi install-ISO with embedded RAID controller driver. It displays "All done" when the ISO is ready.
6. Burn the custom ISO image to a writable CD or USB drive.
   **Note:** Use whatever tool you prefer to burn the CD or USB drive.
   Remove the CD or USB drive after you finish burning the image.

7. On the VMware ESXi machine, insert the custom boot CD/USB, then restart your computer.
8. Follow the on-screen instructions to begin the VMware installation.
9. Complete the VMware installation, following the on-screen instructions.
10. Remove the custom boot CD or USB drive, then reboot your computer.

### 5.8 Installing with Citrix XenServer

**Note:** To install the RAID controller driver with Citrix XenServer, you must burn the XenServer driver iso image to a writeable CD; USB driver disks are not supported for XenServer (see Creating a Driver Disk). You will be prompted to insert the XenServer driver CD twice. You need the XenServer installation DVD (or equivalent virtual media/iso image) to complete this task. You must have administrator privilege to install the driver image.

To install the RAID controller driver while installing Citrix XenServer:

1. On the machine where you want to install the OS and RAID controller driver, insert the XenServer installation DVD, then restart your computer.
2. When prompted to add a driver, press F9.
3. Remove the XenServer installation DVD and insert the driver CD.
4. When the driver update is complete, remove the driver CD and insert the XenServer installation DVD.
5. Continue the XenServer installation, following the on-screen instructions.
6. When prompted to add a driver (at the end of the OS installation), remove the XenServer installation DVD and insert the driver CD.
7. Complete the XenServer installation, following the on-screen instructions.
8. Remove the driver CD, then reboot your computer.
6 Installing the Driver on an Existing Operating System

This chapter explains how to install the RAID controller driver on an existing operating system.

Note:

1. To install the driver while you're installing an operating system, see Installing the Driver and an Operating System on page 24.

2. To install the Linux drivers from source with Dynamic Kernel Module Support (for persistence across across kernel updates), download the Linux Driver Source Code package from the support page for your product at start.microsemi.com, then follow the instructions in the embedded Readme.

6.1 Download the Driver Package

Complete these steps to download the drivers for your operating system(s):

1. Open a browser window, then type start.microsemi.com in the address bar.
2. Enter your product or adapter model number, then select HBA 1000.
3. Select your operating system version, for instance, Microsoft Windows Server 2012 x64 or Red Hat Enterprise Linux 7; then select the appropriate driver from the list.
4. Download the HBA 1000 Series driver package.
5. When the download completes, extract the package contents to a temporary location on your machine. Each driver is stored in a separate folder (\windows 2012, \rhel6, \rhel7, and so on).

   Note: See the Release Notes for a complete list of available driver files.

6.2 Creating a Driver Disk

Create a driver disk by completing the steps below. You will need a USB flash drive to complete this task.

   Note: For VMware and XenServer, see Installing with VMware and Installing with Citrix XenServer on page 28.

1. Change to the driver directory for your operating system version.
2. Write the driver binary file to a USB flash drive (assuming the USB drive is /dev/sdc on Linux systems).

<table>
<thead>
<tr>
<th>Options</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>rhel6/centos6</td>
<td>gunzip hpsa-3.4.10-110.rhel6u5.x86_64.dd.gz</td>
</tr>
<tr>
<td></td>
<td>dd if=hpsa-3.4.10-110.rhel6u5.x86_64.dd of=/dev/sdc</td>
</tr>
<tr>
<td>rhel7/centos7</td>
<td>gunzip hpsa-3.4.10-115.rhel7u0.x86_64.dd.gz</td>
</tr>
<tr>
<td></td>
<td>dd if=hpsa-3.4.10-115.rhel7u0.x86_64.dd of=/dev/sdc</td>
</tr>
<tr>
<td>sles11</td>
<td>gunzip hpsa-3.4.10-110.sles11sp3.x86_64.dd.gz</td>
</tr>
<tr>
<td></td>
<td>dd if=hpsa-3.4.10-110.sles11sp3.x86_64.dd of=/dev/sdc</td>
</tr>
<tr>
<td>sles12</td>
<td>gunzip hpsa-3.4.10-110.sles12sp0.x86_64.dd.gz</td>
</tr>
<tr>
<td></td>
<td>dd if=hpsa-3.4.10-110.sles12sp0.x86_64.dd of=/dev/sdc</td>
</tr>
</tbody>
</table>
### Options Description

**ubuntu14.04**
- gunzip hpsa-3.4.11-100.ubuntu14.04.x86_64.img.gz
- dd if=hpsa-3.4.11-100.ubuntu14.04.x86_64.img of=/dev/sdc1

**windows**
- winzip HpCISSs3.4.10.110.64_pass4.zip
- cp hpsa.inf hpsa2.inf <usb drive>

3. Remove and label the driver disk.
4. Continue the installation with the instructions for your operating system.

### 6.3 Installing on Windows

**Note:** The following instructions apply to all supported Windows operating systems.

To install the driver on Windows:

1. Start or restart Windows.
2. In the Control Panel, launch the Device Manager, right-click on the SAS Controller listed under Other Devices, then select **Update Driver Software**.
3. Insert the driver disk, then select **Browse my computer for driver software**.
4. Browse to the driver disk location, then click **Next**.
5. Select the driver from the list, then click **Next**.
6. When the installation is complete, remove the driver disk and restart your computer.

### 6.4 Installing on Red Hat, CentOS, or SuSE Linux

**Note:** If your Red Hat 7, SLES 11 SP3, or SLES 12 system is booted with uEFI Secure Boot, you need to add a public key to the MOK list (Machine Owner Key) before completing the steps below:

```
mokutil --import aacraid_key_pub.der
```

Enter and confirm a password for the MOK enrollment request, reboot, then complete the enrollment from the uEFI console.

Enter the password you associated with this request (using mokutil), or enter your root password, then confirm the enrollment. Once the key is on the MOK list, it is propagated automatically to the system key ring for this and subsequent reboots (that is, it persists), when uEFI Secure Boot is enabled.

To install the driver on Red Hat Linux, CentOS, or SuSE Linux:

1. Insert and mount the driver disk (assuming the USB drive is /dev/sdal):

```
mount /dev/sdal /mnt/usb
```

2. *(SLES 11 SP3, SLES 12 only)* Install the `aacraid-ueficert` RPM:

```
rpm -ivh mount-point/xxx/aacraid-ueficert-<OS VERSION>-1.2.1-XXXXX.<OS ARCH>.rpm
```

where `mount-point` is the mount point on the Linux system and `xxx` is the driver path.

3. Install the driver RPM for your operating system:
Installing on Oracle Linux

Note: The release package includes a driver RPM for UEK kernels only.

To install the driver on Oracle Linux:

1. Oracle Linux 6.5 Only:
   a) Reboot the OS.
   b) Select the UEK kernel image to boot.

2. Insert and mount the driver disk (assuming the USB drive is /dev/sda1):
   
   ```
   mount /dev/sda1 /mnt/usb
   ```
   
   Note: Be sure the USB driver disk includes both RPMs (see Creating a Driver Disk on page 24).

3. Install the UEK driver rpm:

   ```
   rpm -ivh mount-point/xxx/kmod-aacraid-UEK-<OS Version>-1.2.1-XXXXX.<OS Arch>-rpm
   ```
   
   where mount-point is the mount point on the Linux system, and xxx is the driver path.

4. Restart the system.

5. (Oracle Linux 6.5) Select the kernel image to boot (UEK).

Installing on Ubuntu Linux

Note: For driver installation on Ubuntu Linux, you may need to create the root account and password. Enter these commands: `sudo bash; sudo passwd root`. You must have root privilege to install the driver image.

Note: Microsemi’s pre-built driver supports the kernel that is delivered as part of the ISO. For other kernels, use DKMS process.

To install the driver on Ubuntu Linux:

1. Update the Ubuntu package index:
   
   ```
   sudo apt-get update
   ```

2. Load the Ubuntu unpacking tools:
   
   ```
   sudo apt-get install build-essential
   ```

3. Insert and mount the driver disk (assuming the USB drive is /dev/sda1):
   
   ```
   mount /dev/sda1 /mnt/usb
   ```

4. Install the DEB driver package (where xxxxx is the build number):
   Ubuntu 11:
   
   ```
   sudo dpkg -i
   /mnt/usb/aacraid-1.2.1-xxxxx-Ubuntu11.10+12.04+12.04.1+12.04.2-all.deb
   ```
Ubuntu 14:
```
sudo dpkg -i /mnt/usb/aacraid-1.2.1-xxxxx-Ubuntu14.10-x86_64.deb
```

Ubuntu 16:
```
sudo dpkg -i /mnt/usb/aacraid-1.2.1-xxxxx-Ubuntu16.10-x86_64.deb
```

5. Reboot your computer to ensure the driver loaded correctly.
6. Continue with Managing Your Storage Space.

### 6.7 Installing on VMware

**Note:** You must remove the old driver before you can install the new one. You must have root privilege to install the new driver.

**Note:** To copy the driver VIB file to the VMware ESXi server (in Step 2 below), you must have access to a remote copy utility, such as WinSCP, putty, or Linux scp.

To install the driver on VMware:

1. At the VMware console screen, type these commands to remove the old driver from a VMware 5.x or VMware 6.0 system:

   ```
esxcli software vib list | grep -i aacraid (list driver packages)
esxcli software vib remove --vibname=scsi-aacraid --maintenance-mode (remove package)
```

2. Using a remote copy utility, copy the driver VIB file for your operating system version to a local directory on the ESXi server. This example uses Linux scp to copy the driver to /tmp/aacraid (where xxxx is the build number):

   VMware ESXi 5.5:

   ```
   scp /mnt/sda1/linux/driver/vmware-esxi-drivers-scsi-aacraid-550.5.2.1.xxxxx.-1.5.5.1331820.x86_64.vib root@<esx-server-ip>:/tmp/aacraid
   ```

   VMware ESXi 6.0:

   ```
   scp /mnt/sda1/linux/driver/vmware-esxi-drivers-scsi-aacraid-600.6.2.1.xxxxx.-1.0.6.2159203.x86_64.vib root@<esx-server-ip>:/tmp/aacraid
   ```

3. Install the VIB module (where xxxx is the build number):

   VMware ESXi 5.5:

   ```
esxcli software vib install -f -v
file:/tmp/aacraid/vmware-esxi-drivers-scsi-aacraid-550.5.2.1.xxxxx.-1.5.5.1331820.x86_64.vib
```

   VMware ESXi 6.0:

   ```
esxcli software vib install -f -v
file:/tmp/aacraid/vmware-esxi-drivers-scsi-aacraid-600.6.2.1.xxxxx.-1.0.6.2159203.x86_64.vib
```

4. Reboot your computer.
6.8 Installing on Citrix XenServer

Note: To copy the driver RPM file to XenServer (in Step 1 below), you must have access to a remote copy utility, such as WinSCP, putty, or Linux scp. You must have root privilege to install the driver.

To install the driver on XenServer (where xxxxx is the build # and .x is the OS version):

1. Using a remote copy utility, copy the driver RPM file to a local directory on XenServer. This example uses Linux scp to copy the driver to /tmp/aacraid:

   `scp /mnt/sda1/linux/driver/citrix-aacraid-1.2.1-xxxxx.xen-6.x.rpm root@<xen-server-ip>:/tmp/aacraid`

2. Install the driver module rpm:

   `rpm -ivh /tmp/aacraid/citrix-aacraid-1.2.1-xxxxx.xen-6.x.rpm`

3. Reboot your computer.
7 Installing Dynamic Kernel Module Support

This chapter explains how to install the DKMS driver.

7.1 Installing the DKMS Deb Package on Ubuntu Systems

The following steps are for installing the DKMS deb package on an Ubuntu System.

1. Since DKMS involves changing system-level kernel files, it requires superuser permissions.
   
   $ sudo su

2. DKMS requires build-essential (which installs all packages that are required to build an executable on Ubuntu), the current kernel headers, and DKMS.
   
   # apt-get install dkms build-essential linux-headers-`uname -r`

3. Once the dependency packages have been installed, the DKMS deb package can be installed. Now DPKG calls DKMS internally, which builds the driver and installs it to the current kernel. XXXXX is the driver release version.
   
   # dpkg -i aacraid-dkms_1.2.1.XXXXX_all.deb

4. After the DKMS install is done, the system needs to be rebooted for the new driver to take effect.
   
   # apt-get install linux-headers-`uname -r`

   **Note:** When the Ubuntu Linux kernel is updated, then DKMS will attempt to build the driver for the newly updated kernel and fail, since the headers for the new kernel have not been installed yet. Reboot the system and select the newly updated kernel. Once it boots up, previous command will install headers for the updated kernel and install AACRAID driver on it as well.

7.2 Installing the DKMS RPM Package

The DKMS executable package is available in the EPEL repository.

1. Retrieve the EPEL repository file (the "X" denotes the major version).
   

2. Install the EPEL repository.
   
   $ sudo rpm -Uvh epel-release-latest-X.noarch.rpm

3. Install DKMS.
   
   $ sudo yum install dkms

7.3 DKMS Reference

This section contains information on the other functions of DKMS.

1. Build and install a driver.
   
   # dkms add -m aacraid -v 1.2.1.XXXXX
   # dkms build -m aacraid -v 1.2.1.XXXXX
   # dkms install -m aacraid -v 1.2.1.XXXXX

2. Build a driver for a different system other than native.
# dkms build -k 2.4.21-4.ELamp -m aacraid -v 1.2.1.XXXXX
# dkms install -k 2.4.21-4.ELamp -m aacraid -v 1.2.1.XXXXX

3. Make a driver disk from a set of built drivers.

# dkms mkdriverdisk -k 2.4.21-4.ELBOOT,2.4.21-4.ELamp,2.4.21-4.EL \ 
   -d redhat -m aacraid -v 1.2.1.52009
# dkms mkdriverdisk -k 2.6.11.4-20a-default,2.6.11.4-20a-smp \ 
   -d suse -m aacraid -v 1.2.1.52009

4. Check current status of DKMS.

# dkms status
8 Solving Problems

This section provides basic troubleshooting information and solutions for solving problems with your Microsemi Adaptec HBA 1000 Series Host Bus Adapter.

8.1 Troubleshooting Checklist

If you encounter difficulties installing or using your Microsemi Adaptec 1000 Series Host Bus Adapter, check these items first:

- With your computer powered off, check the connections to each disk drive, power supply, enclosure, and so on.
- Try disconnecting and reconnecting disk drives from the adapter.
- Check that your adapter is installed in a compatible PCIe expansion slot. To verify the bus compatibility of your adapter, see About Your Host Bus Adapter on page 14.
- Ensure that your adapter is firmly seated and secured in the PCIe expansion slot.
- If your adapter is not detected during system boot, try installing it in a different compatible expansion slot. (See Installing the Host Bus Adapter on page 22 for instructions.)
- Did the driver install correctly? It may need to be reloaded after a reboot or kernel update; see Installing Linux Drivers with Dynamic Kernel Module Support.
- If you have external disk drives (or other devices), are they powered on?
- Check the Release Notes for compatibility issues and known problems.

If you are still unable to resolve a problem, contact Microsemi Support.

8.2 Resetting the Adapter

You may need to reset your HBA 1000 Series adapter if it becomes inoperable or if a firmware upgrade is unsuccessful. HBA 1000 Series adapters support a reset protocol called HDA mode flash. For information about HDA mode, contact your support representative. To locate the HDA mode jumper on your adapter, see the board illustrations in About Your Host Bus Adapter on page 14.
A Using the SAS/SATA Configuration Utility

The SAS/SATA Configuration utility is a BIOS-based utility that you can use to manage your RAID controller and the devices attached to it. It comprises a set of tools for creating and managing arrays, viewing and modifying adapter properties, and managing disk drives and spares.

The SAS/SATA Configuration utility is a BIOS-based utility that you can use to manage your RAID controller and the devices attached to it. It comprises a set of tools for viewing and modifying adapter properties, viewing disk drive properties, and flashing the HBA firmware.

A.1 Running the SAS/SATA Configuration Utility: Ctrl-A or uEFI/HII?

Your Microsemi RAID controller supports two interfaces to the BIOS-level controller configuration options described in this section: Ctrl-A and uEFI/HII.

On servers that support the Unified Extensible Firmware Interface, or uEFI (version 2.10 or higher), the BIOS-level configuration options are presented with a uEFI/HII interface (Human Interaction Infrastructure), rather than Microsemi’s legacy Ctrl-A interface. uEFI/HII provides an architecture-independent mechanism for initializing add-in cards, like the RAID controller, and rendering contents to the screen in a uniform way.

To access the RAID controller configuration options with the Ctrl-A interface, start or restart your computer. When prompted, press Ctrl+A, then select your controller from the list. The Ctrl-A BIOS main menu is displayed.

In the uEF/HII interface, the server’s standard BIOS provides access to the RAID controller configuration options. How you access the BIOS varies, depending on the server manufacturer, but typically it’s started by simply pressing DEL. Once you enter setup, navigate to the "Advanced" menu (below, left), then select your controller from the list. The uEF/HII main menu is displayed (below, right).
From that point on, the uEFI/HII menus and the Ctrl-A menus for configuring your controller are similar. For example, the Array Configuration menu (uEFI/HII) and the Logical Device Configuration menu (Ctrl-A) contain the same options for creating and managing arrays (though the task flow may differ); the Disk Utilities menu contains the same options for managing disk drives; and so on.

From that point on, the uEFI/HII menus and the Ctrl-A menus for managing your controller are similar. For example, the Controller Configuration menu (uEFI/HII) and the Controller Settings menu (Ctrl-A) contain similar options for viewing and modifying controller properties (though the task flow may differ); the Disk Utilities menu contains similar options for working with disk drives; and so on.

Note: The Administration menu is available only with the uEFI/HII interface. The Array Configuration menu (uEFI/HII) and the Logical Device Configuration menu (Ctrl-A) are not supported on the RAID controller.

In both interfaces, all the tools are menu-based and instructions for completing tasks appear on-screen. Menus can be navigated using the arrows, Enter, Esc, and other keys on your keyboard.

This appendix provides instructions for navigating and completing tasks with the uEFI/HII interface. To complete tasks with the Ctrl-A interface:

- Refer to the on-screen instructions for keyboard navigation and selection options.
- Refer to the option descriptions in this section for details about individual configuration settings.

### A.2 Modifying RAID controller Settings

To modify the RAID controller settings, start the SAS/SATA Configuration Utility, select **Controller Configuration** from the main menu, then select **Controller Properties** or **Advanced Controller Properties**. You can set the options in the table below.

```markdown
<table>
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<tr>
<th>Main</th>
<th>Advanced</th>
<th>Event Logs</th>
<th>IPMI</th>
</tr>
</thead>
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<tr>
<td>Boot Feature</td>
<td>CPU Configuration</td>
<td>Chipset Configuration</td>
<td>SATA Configuration</td>
</tr>
<tr>
<td>RAID Configuration</td>
<td>SCU Configuration</td>
<td>PCIe/PCI/PnP Configuration</td>
<td>Super IO Configuration</td>
</tr>
<tr>
<td>Serial Port Console Redirection</td>
<td>ACPI Settings</td>
<td>ME Subsystem</td>
<td>Intel RSTe SCU Controller</td>
</tr>
<tr>
<td>Adapted SmartIOC 2000</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
```

Using the SAS/SATA Configuration Utility
<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Transformation Priority</td>
<td>Sets the priority for array expansion:</td>
</tr>
<tr>
<td></td>
<td>• Low: normal system operations take priority over array expansion</td>
</tr>
<tr>
<td></td>
<td>• Medium: normal system operations and array expansion get equal priority</td>
</tr>
<tr>
<td></td>
<td>• High: expansion takes precedence over all other system operations</td>
</tr>
<tr>
<td>Rebuild Priority</td>
<td>Sets the priority for rebuilding a failed logical drive:</td>
</tr>
<tr>
<td></td>
<td>• Low: normal system operations take priority over rebuilds</td>
</tr>
<tr>
<td></td>
<td>• Medium: normal system operations and rebuilds get equal priority</td>
</tr>
<tr>
<td></td>
<td>• Medium High: rebuilds get higher priority than normal system operations</td>
</tr>
<tr>
<td></td>
<td>• High: rebuilds take precedence over all other system operations</td>
</tr>
<tr>
<td>Surface Scan Analysis Delay</td>
<td>Determines the time, in seconds, that a controller must be inactive before a surface scan analysis is started on the physical drives connected to it. The scanning process checks physical drives for bad sectors and, in fault-tolerant logical drives, such as RAID 5, it also verifies the consistency of parity data. Delay value ranges from 1–30 seconds.</td>
</tr>
<tr>
<td>Surface Scan Count</td>
<td>Sets the surface scan count for the controller. Set the value to &quot;1&quot; to disable the feature.</td>
</tr>
<tr>
<td></td>
<td><strong>Caution:</strong> Disabling Surface Scan Analysis is not recommended as it will prevent the controller from proactively finding and correcting disk surface errors, which may lead to data loss.</td>
</tr>
<tr>
<td>Physical Drive Write Cache State</td>
<td>Enables and disables physical drive write cache for all drives on the controller.</td>
</tr>
<tr>
<td>Spare Activation Mode</td>
<td>Sets the spare activation mode to activate on failure or predictive failure activation.</td>
</tr>
<tr>
<td>Connector Mode (CN0:CN3)</td>
<td>Configures the controller connectors to different operating modes:</td>
</tr>
<tr>
<td></td>
<td>• HBA: exposes physical drives to the operating system</td>
</tr>
<tr>
<td></td>
<td>• RAID: exposes only RAID volumes to the operating system</td>
</tr>
<tr>
<td></td>
<td>• Mixed: exposes RAID volumes and physical drives to the operating system</td>
</tr>
<tr>
<td>Advanced Properties:</td>
<td></td>
</tr>
<tr>
<td>Degraded Mode Perf Optimization</td>
<td>For degraded RAID 5 logical drives, enabling this setting directs the controller to attempt to improve performance of large read requests by buffering physical drive requests. Disabling this setting forces the controller to read from the same drives multiple times.</td>
</tr>
<tr>
<td>Physical Drive Elevator Sort</td>
<td>Sets the behavior of the drive's write Elevator sort algorithm, a scheduling optimization that prioritizes I/O requests such that disk arm and head motion continues in the same direction. Enabling the elevator sort improves seek times and disabling the elevator sort improves throughput.</td>
</tr>
<tr>
<td>Inconsistent Repair Policy</td>
<td>Sets the surface analysis inconsistency repair policy for RAID 5 when the controller detects that the parity information does not match the data on the drives. Disabling the repair policy directs the controller to update the parity information, leaving the data untouched. Enabling the repair policy directs the controller to update the data on the drives based on the parity information.</td>
</tr>
<tr>
<td>MNP Analysis Delay</td>
<td>Sets the Monitor and Performance Analysis delay for the controller, in seconds. Set the value to zero to disable Monitor and Performance Analysis. Default is 60 minutes (3600 seconds).</td>
</tr>
<tr>
<td>HDD Flexible Latency Optimi-</td>
<td>Enables flexible latency optimization for HDDs. When FLS is enabled, the controller detects high-latency I/O requests and applies a cutoff, or threshold, value, after</td>
</tr>
<tr>
<td>zation</td>
<td></td>
</tr>
</tbody>
</table>
A.3 Clearing the Controller Configuration

Clearing the controller configuration destroys the controller meta-data, including array configurations, partition information, and so on.

**Caution:** When you clear the controller configuration, all data on the attached media (SSD/HDD) will no longer be accessible and cannot be recovered. Be sure you no longer need the data on the controller before proceeding!

To clear the controller configuration:

1. Start the SAS/SATA Configuration Utility in uEFI mode (see Running the SAS/SATA Configuration Utility: Ctrl-A or uEFI/HII? on page 37).
2. Select your controller, then press Enter.
3. From the main menu, select Controller Configuration.
4. Select Clear Controller Configuration.
5. Select Clear Config Submit.

A.4 Viewing Disk Drive Properties

Use the Disk utilities to view the disk drives on a controller and view disk drive properties.

To view disk drive properties:

1. Start the PMC SAS/SATA Configuration Utility in uEFI mode (see Running the SAS/SATA Configuration Utility: Ctrl-A or uEFI/HII? on page 37).
2. Select your controller, then press Enter.
3. From the main menu, select Disk Utilities.
4. Use the arrow keys to select a disk drive.
5. Press Esc to return to the previous menu.

A.5 Updating the RAID controller Firmware

**Note:** This option is available only in the uEFI interface.

To update the RAID controller firmware:

1. Copy the firmware binary file (.bin) to a USB flash drive, then connect the USB drive to the machine. Alternatively, copy the firmware binary to a known location on your machine.
2. Start the SAS/SATA Configuration Utility in uEFI mode (see Running the SAS/SATA Configuration Utility: Ctrl-A or uEFI/HII? on page 37), select the controller you want to flash, then press Enter.
3. From the main menu, select **Administration**, then select **Flash Controller Firmware**.

4. Select **Continue with flashing Firmware**.

5. Select the storage device where the firmware binary file is located (the USB drive, for instance), navigate the folder hierarchy, then select the firmware binary file.
   The firmware is sent to the controller.

6. When the update is complete, reboot the server.
B  Driver Event Logging on Windows and Linux


On Windows systems, events are logged using the standard Windows event logging feature (supported by the Windows Storport driver). To view the events, use the Windows Event Viewer, accessible from the Administrative Tools option in the Control Panel.

Each log entry includes the event message, event level (Information, Warning, Error), failed command, and error code, such as the BLED code. It also includes the date and time of the event, event source, Event ID, and event description. Table 4 • Windows Driver Initialization Failure Events describes the driver events on Windows.

Table 4 • Windows Driver Initialization Failure Events

<table>
<thead>
<tr>
<th>Event Description</th>
<th>Event Level</th>
<th>Event ID (hex)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>FW Not Up &amp; Running</td>
<td>Warning</td>
<td>0x35</td>
<td>Driver Init: FW Not Up &amp; Running BLED 0x&quot;BLED CODE</td>
</tr>
<tr>
<td>Adapter Ready for Config</td>
<td>Warning</td>
<td>0x36</td>
<td>Driver Init: CT_CONFIG_STATUS_READY (&quot;command code&quot;) Failed</td>
</tr>
<tr>
<td>Adapter Get Config Status</td>
<td>Warning</td>
<td>0x37</td>
<td>Driver Init: CT_GET_CONFIG_STATUS (&quot;command code&quot;) Failed</td>
</tr>
<tr>
<td>Adapter Commit Config Status</td>
<td>Warning</td>
<td>0x38</td>
<td>Driver Init: CT_COMMIT_CONFIG (&quot;command code&quot;) Failed</td>
</tr>
<tr>
<td>Adapter Init Structure Status</td>
<td>Warning</td>
<td>0x39</td>
<td>Driver Init: ADAPTER_INIT_STRUCT_REVISION (&quot;Init struct version number&quot;) Failed</td>
</tr>
<tr>
<td>Container Config Command Status</td>
<td>Warning</td>
<td>0x40</td>
<td>Driver Init: VM_ContainerConfig (&quot;command code&quot;) Failed</td>
</tr>
<tr>
<td>Adapter Init Failed Timeout</td>
<td>Error</td>
<td>0x41</td>
<td>Driver Init: Timed out, Init Stage # &quot;decimal number&quot; (indicates Init stage at which it failed)</td>
</tr>
</tbody>
</table>

On Linux systems, the driver logs kernel panics, internal diagnostics failures, timeouts, and other initialization failure events (see Table 5 • Linux Driver Initialization Failure Events).

Table 5 • Linux Driver Initialization Failure Events

<table>
<thead>
<tr>
<th>Event Description</th>
<th>Event Level</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>KERNEL_PANIC</td>
<td>Error</td>
<td>Adapter kernel is in panic mode and cannot start up</td>
</tr>
<tr>
<td>SELF_TEST_FAILED</td>
<td>Error</td>
<td>Adapter kernel internal diagnostic failed</td>
</tr>
<tr>
<td>MONITOR_PANIC</td>
<td>Error</td>
<td>Adapter monitor kernel panicked is locked</td>
</tr>
<tr>
<td>Adapter_INIT_TIMEOUT</td>
<td>Error</td>
<td>Adapter failed to provide response or start up during initialization</td>
</tr>
<tr>
<td>FLASH_UPD_PENDING</td>
<td>Error</td>
<td>Adapter is updating the firmware and cannot start yet</td>
</tr>
<tr>
<td>CT_GET_CONFIG_STATUS</td>
<td>Error</td>
<td>Driver failed to retrieve configuration data from the adapter</td>
</tr>
<tr>
<td>CT_COMMINT_CONFIG</td>
<td>Error</td>
<td>Driver failed to commit driver changes to adapter</td>
</tr>
</tbody>
</table>
Driver Event Logging on Windows and Linux

<table>
<thead>
<tr>
<th>VM_ContainerConfig</th>
<th>Error</th>
<th>Driver failed to get information on the disks and mediums attached to the adapter from the adapter kernel</th>
</tr>
</thead>
<tbody>
<tr>
<td>RequestAdapterInfo</td>
<td>Error</td>
<td>Driver failed to get adapter information from the adapter kernel</td>
</tr>
</tbody>
</table>

To view the events, use the Linux `dmesg` command to display the messages in the log files. Each log entry includes the failed command, Linux Internal Device ID, type of event, stage at which the error occurred, and return status of the erroneous function or register.

Example:

```bash
# aacraid 0000:03:00.0: aac_probe_one: Driver Init: KERNEL_PANIC - 50
```

Where:

- `aacraid` - driver name
- `0000:03:00.0` - Linux Internal Device ID
- `aac_probe_one` - Driver function where Error Occurred
- `Driver Init` - Stage at which Error Occurred
- `KERNEL_PANIC` - Type of Event
- `50` - Return status of erroneous function or register
C Safety Information

To ensure your personal safety and the safety of your equipment:

- Keep your work area and the computer clean and clear of debris.
- Before opening the system cabinet, unplug the power cord.

C.1 Electrostatic Discharge (ESD)

Caution: ESD can damage electronic components when they are improperly handled, and can result in total or intermittent failures. Always follow ESD-prevention procedures when removing and replacing components.

To prevent ESD damage:

- Use an ESD wrist or ankle strap and ensure that it makes skin contact. Connect the equipment end of the strap to an unpainted metal surface on the chassis.
- Avoid touching the adapter against your clothing. The wrist strap protects components from ESD on the body only.
- Handle the adapter by its bracket or edges only. Avoid touching the printed circuit board or the connectors.
- Put the adapter down only on an antistatic surface such as the bag supplied in your kit.
- If you are returning the adapter to Microsemi Product Support, put it back in its antistatic bag immediately.

If a wrist strap is not available, ground yourself by touching the metal chassis before handling the adapter or any other part of the computer.
D Technical Specifications

D.1 Environmental Specifications

Note: Microsemi Adaptec HBA 1000 Series adapters require adequate airflow to operate reliably. The recommended airflow is 200 LFM (linear feet per minute), minimum. Forced airflow is required.

<table>
<thead>
<tr>
<th>Specification</th>
<th>Requirements</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ambient temperature</td>
<td>0 °C to 55 °C</td>
</tr>
<tr>
<td>Relative humidity</td>
<td>10% to 90%, non-condensing</td>
</tr>
<tr>
<td>Altitude</td>
<td>Up to 3,000 meters</td>
</tr>
</tbody>
</table>

Note: Ambient temperature is measured 1” from the HBA processor.

D.2 DC Power Requirements

<table>
<thead>
<tr>
<th>Bus Type</th>
<th>Description</th>
<th>Requirements</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCIe</td>
<td>DC Voltage</td>
<td>3.3 V ± 9%, 12 V ± 8%</td>
</tr>
</tbody>
</table>

D.3 Current and Power Requirements

<table>
<thead>
<tr>
<th>Adapter Model</th>
<th>Typical Power</th>
<th>Typical Current</th>
</tr>
</thead>
<tbody>
<tr>
<td>Microsemi Adaptec HBA 1000-8i</td>
<td>9.40W</td>
<td>0.3A @ 3.3 VDC; 0.7A @ 12.0 VDC</td>
</tr>
<tr>
<td>Microsemi Adaptec HBA 1000-8e</td>
<td>8.70W</td>
<td>0.1A @ 3.3 VDC; 0.7A @ 12.0 VDC</td>
</tr>
<tr>
<td>Microsemi Adaptec HBA 1000-8i8e</td>
<td>12.30W</td>
<td>0.1A @ 3.3 VDC; 1.0A @ 12.0 VDC</td>
</tr>
<tr>
<td>Microsemi Adaptec HBA 1000-16i</td>
<td>11.80W</td>
<td>0.3A @ 3.3 VDC; 0.9A @ 12.0 VDC</td>
</tr>
<tr>
<td>Microsemi Adaptec HBA 1000-16e</td>
<td>11.10W</td>
<td>0.1A @ 3.3 VDC; 0.9A @ 12.0 VDC</td>
</tr>
</tbody>
</table>

Note: For the HBA 1000-8e/16e/8i8e, 3.3V current is measured without Active cables. Typical current will increase according to the type and number of Active cables.
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